

6 Edition
Revised &
Updated



A Handbook on

Electrical Engineering



Contains well illustrated
formulae & key theory concepts

for

ESE, GATE, PSUs
& OTHER COMPETITIVE EXAMS





MADE EASY Publications Pvt. Ltd.

Corporate Office: 44-A/4, Kalu Sarai (Near Hauz Khas Metro Station), New Delhi-110016

Contact: 9021300500

E-mail: infomep@madeeasy.in

Visit us at: www.madeeasypublications.org

A Handbook on Electrical Engineering

© Copyright, by MADE EASY Publications Pvt. Ltd.

All rights are reserved. No part of this publication may be reproduced, stored in or introduced into a retrieval system, or transmitted in any form or by any means (electronic, mechanical, photo-copying, recording or otherwise), without the prior written permission of the above mentioned publisher of this book.



First Edition: 2012

Second Edition: 2014

Third Edition: 2015

Fourth Edition: 2019

Reprint: 2020

Reprint: 2021

Fifth Edition: 2022

Sixth Edition: 2023

Director's Message



B. Singh (Ex. IES)

During the current age of international competition in Science and Technology, the Indian participation through skilled technical professionals have been challenging to the world. Constant efforts and desire to achieve top positions are still required.

I feel every candidate has ability to succeed but competitive environment and quality guidance is required to achieve high level goals. At MADE EASY, we help you discover your hidden talent and success quotient to achieve your ultimate goals. In my opinion CSE, ESE, GATE & PSUs exams are tools to enter in to the main stream of Nation serving. The real application of knowledge and talent starts, after you enter in to the working system. Here at MADE EASY you are also trained to become winner in your life and achieve job satisfaction.

MADE EASY alumni have shared their winning stories of success and expressed their gratitude towards quality guidance of MADE EASY. Our students have not only secured All India First Ranks in ESE, GATE and PSUs entrance examinations but also secured top positions in their career profiles. Now, I invite you to become an alumnus of MADE EASY to explore and achieve ultimate goal of your life. I promise to provide you quality guidance with competitive environment which is far advanced and ahead than the reach of other institutions. You will get the guidance, support and inspiration that you need to reach the peak of your career.

I have a true desire to serve the Society and the Nation easing path of the education for the people of India.

After a long experience of teaching Electrical Engineering over a period of time, MADE EASY team realised that there is a need of a good *Handbook* which can provide the crux of Electrical Engineering in a concise form to the student to brush up the formulae and important concepts required for ESE, GATE, PSUs and other competitive examinations. This *handbook* contains all the formulae and important theoretical aspects of Electrical Engineering. It provides much needed revision aid and study guidance before examinations.

B. Singh (Ex. IES)
CMD, MADE EASY Group

A Handbook on Electrical Engineering

Chapter 1 :

Power Systems 1-49

- I. Supply System..... 1
- II. Line Parameters.....3
- III. Performance of Transmission Line.... 13
- IV. Concept of Corona 21
- V. Mechanical Design of Overhead Lines..... 23
- VI. Balanced and Unbalanced Faults..... 25
- VII. Power System Stability..... 30
- VIII. Power System Transients..... 32
- IX. Economic Load Dispatch..... 37
- X. Underground Cable 38
- XI. Protective Relays 42
- XII. Circuit Breakers..... 45
- XIII. Generating Power Stations..... 46
- XIV. Loads and Load Curves..... 48

Chapter 2 :

Electrical Machines..... 50-102

- I. Transformers..... 50
- II. Electromagnetic System..... 63
- III. Basic Concepts in Rotating Electrical Machines..... 64
- IV. D.C. Machines..... 66
- V. Polyphase Induction Motors..... 76
- VI. Polyphase Synchronous Machines... 85
- VII. Single Phase Induction Machine..... 97
- VIII. Special Machines..... 102

Chapter 3 :

Power Electronics 103-161

- I. Power Electronics..... 103
- II. Thyristor 109
- III. Thyristor Commutation Techniques 116
- IV. Diode Circuits and Rectifiers..... 121

- V. Phase Controlled Rectifiers 128
- VI. Choppers..... 143
- VII. Inverters 149
- VIII. AC Voltage Controllers 157
- IX. Electric Drives..... 160

Chapter 4 :

Measurements and Instrumentation 162-206

- I. Characteristics of Instruments and Measurement Systems..... 162
- II. Circuit Components (Resistors, Inductors, Capacitors) 167
- III. Galvanometers..... 169
- IV. Analog Meters..... 171
- V. Instrument Transformers..... 178
- VI. Measurement of Power and Wattmeters 181
- VII. Measurement of Resistance 185
- VIII. A.C. Bridges 191
- IX. Magnetic Measurements 196
- X. Electronic Instruments..... 197
- XI. Cathode Ray Oscilloscope 198
- XII. High Frequency Measurements 201
- XIII. Transducers 202
- XIV. Digital Instrumentation..... 204

Chapter 5 :

Network Theory 207-241

- I. Basic Definitions & Circuits Element ...207
- II. Network Laws and Theorems 215
- III. Graph Theory 221
- IV. Laplace Transform Analysis and Circuit Transients 224
- V. Resonance 229
- VI. Magnetically Coupled Circuit 232
- VII. Two Port Network..... 234
- VIII. Miscellaneous..... 237

Chapter 6 :

Control Systems 242-276

I. Introduction.....	242
II. Mathematical Modelling.....	243
III. Transfer function.....	249
IV. Time Response Analysis of C.S.	254
V. Stability in Time-Domain	261
VI. Industrial Controller.....	264
VII. Compensator.....	267
VIII. Frequency Response Analysis	269
IX. State Space Analysis	275

Chapter 7 :

Signals and Systems 277-308

I. Introduction to Signals	277
II. Linear Time Invariant Systems.....	283
III. Fourier Series.....	286
IV. Fourier Transform.....	291
V. Laplace Transform.....	295
VI. Discrete Time Fourier Transform.....	298
VII. Z-Transform.....	299
VIII. Discrete Fourier Transform	302
IX. Digital Filters.....	303
X. Miscellaneous.....	306

Chapter 8 :

Analog Electronics..... 309-370

I. Semiconductor Physics.....	309
II. Junction Diode Characteristics	317
III. BJT Characteristics.....	327
IV. Transistor Biasing Circuits	332
V. BJT as an Amplifier	337
VI. Junction Field Effect Transistors	339
VII. Metal Oxide Semiconductor Field Effect Transistor.....	343
VIII. Transistor Hybrid Model.....	346
IX. Feedback Amplifiers	348
X. Operational Amplifiers.....	352
XI. Large Signal Amplifiers.....	360
XII. The Signal Generators and Wave Shaping Circuits.....	363

Chapter 9 :

Digital Electronics 371-422

I. Number System and Codes.....	371
II. Logic Gates.....	376
III. Boolean Algebra and Reduction Techniques.....	383
IV. Digital Logic Circuits	387
V. Sequential Circuits.....	394
VI. Registers.....	399
VII. Counters.....	400
VIII. Digital ICs Family	404
IX. DACs and ADCs.....	411
X. Miscellaneous.....	418

Chapter 10 :

Electrical Materials 423-449

I. Dielectric Properties of Insulating Materials.....	423
II. Dielectric Breakdown	431
III. Magnetic Properties of Materials.....	433
IV. Conductive Materials.....	438
V. Semiconductors	442
VI. Insulating Materials.....	443
VII. Structure of Materials.....	446
VIII. Ceramic Materials	448

Chapter 11 :

Electromagnetic Theory 450-449

I. Vector Calculus	450
II. Cartesian Coordinate System & Vector Calculus.....	451
III. Electrostatics.....	457
IV. Magnetostatics	465
V. Time-Varying Electromagnetic Fields.....	469
VI. Electromagnetic Wave Propagation	472
VII. Transmission Lines.....	480

Chapter 12 :

Microprocessors484-526

- I. Introduction484
- II. Architecture of 8085485
- III. Instruction Set and Data Formats ...492
- IV. Interrupts508
- V. Interfacing with Microprocessor510
- VI. Introduction to 8086.....514
- VII. Microcontroller518

Chapter 13 :

Communication

Systems527-546

- I. Basics527
- II. Fourier Series, Energy and Signals528

- III. Analog Modulation530
- IV. Pulse Modulation537
- V. Digital Carrier Modulation540
- VI. Random Variables and Noise543

Chapter 14 :

Computer

Fundamentals 547-571

- I. Data Representation547
- II. Computer Architecture.....548
- III. Memory Organization553
- IV. Networking Fundamental562
- V. Programming Elements.....563
- VI. Operating System Concepts564

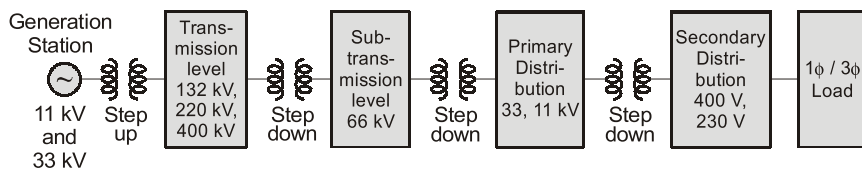
■■■■

Power Systems

1

I Supply System

Basic Structure of Power System



- Generating stations are interconnected by the lines.
- Transmission lines, when interconnected with each other, becomes transmission networks.
- The combined transmission and distribution network is known as the “power grid”.

Effect of System Voltage on Transmission of Power

- Power loss in the line is inversely proportional to the system voltage and power factor both.
- Percentage voltage drop in resistance decreases with the increase in the system voltage.
- Weight of the conductor material for the line will decrease with the increase in supply voltage and power factor.
- Efficiency of transmission, increases with the increase of supply voltage and power factor.
- Higher supply voltages also enhance the system stability.
- The problems encountered with high voltages are the insulation of the equipment, corona, radio and television interference.
- The voltage level of a system is therefore governed by the amount of power to be transmitted and the length of the line.

Voltage Level

- Low voltage —
 - 230 V (1- ϕ)
 - 400 V (3- ϕ)
- High voltage —
 - 11 kV
 - 33 kV

- Extra high voltage: 66 kV, 132 kV, 220 kV.
- Modern EHV: 400 kV
- Ultra high voltage: 765 kV and above.

Conductor Used for Transmission Line

- Copper conductor
- ACSR : Aluminium conductor steel reinforced.
- ACAR : Aluminium conductor alloy reinforced.
- AAAC : All Aluminium alloy conductor.
- Expanded ACSR conductor: Normally used for EHV lines.
- AAC : All Aluminium conductors.

Types of Conductor

- Solid conductor: It has high skin effect.
- Hollow conductor: Preferred under heavy current, i.e., more than 1000 Amp.
- Stranded conductor.
- Composite standard conductor: used for voltage ≤ 220 kV.
- Bundle conductor: Used for voltage > 275 kV.

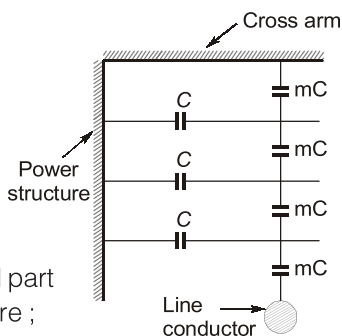
Advantage of Bundle Conductor

- Self distance (GMR) increased without change in mutual distance.
- Voltage gradient reduced so corona loss reduce.
- It reduces the interference with nearby communication line.
- Inductance (L) of transmission line reduces and capacitance (C) increases.
- Surge impedance, i.e., $Z_s = \sqrt{\frac{L}{C}}$ decreases.
- Power system stability increases.

Insulators

Over head line insulators provide the required insulation to the line conductors from each other and from the supporting structures electrically. Most commonly used materials are porcelain, toughened glass and steatite,

where, $C \rightarrow$ Capacitance between metal part of the insulator and tower structure ;
 $mC \rightarrow$ Capacitance of each insulator disc.
 $mC > C$



Note:

- ☑ The stress experienced by the disc near the power conductor is more than the stress experience by the disc near the cross-arm.

String Efficiency

$$\text{String efficiency} = \frac{\text{Voltage across the whole string}}{n \times (\text{Voltage across the unit adjacent to line conductor})}$$

where, $n \rightarrow$ Number of insulator discs in the string

String efficiency also defined as

$$\% \eta = \frac{\text{Flashover voltage of the string}}{n \times \text{flashover voltage of one string}} \times 100$$

Note:

- ☑ As the number of disc increases string efficiency decreases.

Methods of Equilising Potential Across Each Disc

- Increase the length of cross arm.
- Capacitance grading or grading of units.
- Use of grading rings or static shielding.

Remember:

- ☑ For static shielding the capacitance from the shield to the K_{th} link from the top

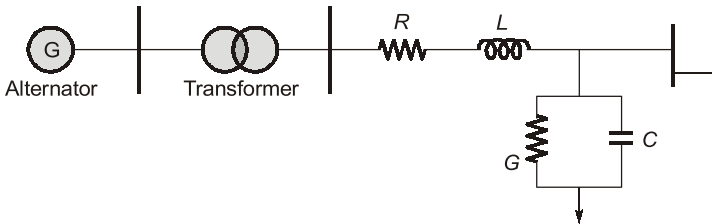
$$C_K = \frac{KC}{n-K} \quad (\because n = \text{number of disc})$$

Types of Insulator

- **Pin type insulator:** Pin type insulator operate satisfactory upto 25 kV.
- **Multipine type insulator:** Operates upto 33 kV
- **Suspension type insulator:** A suspension insulator is designed to operate at 11 kV.
- **Strain type insulator:** Strain type insulator mechanically strong. It is used when direction of transmission line changes across river crossing and at the dead end of the transmission line.
- **Shackle type:** Shackle type insulator are used in low tension cable. These insulator can be operated either horizontally or vertically.

II Line Parameters

Transmission line is a carrier on which bulk amount of power from a remote generating station to the operative areas is being carried out.



Transmission line is

- series combination of resistance (R) and inductance (L) and
- Parallel combination of shunt conductance (G) and capacitance (C).

Note:

- The line parameter of transmission line is calculated in per unity or per km and are constant for entire line length.
- The shunt conductance is caused by leakage current.
- In transmission line if $G = 0$ means leakage current is assume to be zero.
- Power loss in the conductor is only due to series resistance.
- Power transmission capacity of the line is mainly governed by the series inductance.

- **Resistance of a conductor,** $R_{\text{eff}} = \frac{\text{Power loss in conductor}}{I^2}$ ohms

where, $R_{\text{eff}} \rightarrow$ Effective resistance of the conductor

- **D.C. Resistance of a Conductor,** $R_{dc} = \rho \frac{l}{A}$ ohms

where, $\rho \rightarrow$ Resistivity of conductor, $\Omega\text{-m}$; $l \rightarrow$ Length of conductor, metre; $A \rightarrow$ Cross-sectional area, m^2

Note:

- ☒ The effective resistance is equal to the dc resistance of the conductor only if the current is uniformly distributed throughout the cross-sectional area of the conductor (i.e. for DC only).

Skin Effect

If DC is passed in a conductor, the current density is uniform over the cross-section of the conductor but when an alternating current flows through a conductor, the distribution tends to become non uniform. There is a tendency of the current to crowd near the surface of the conductor. This phenomenon is called “skin effect”. The effective conductor resistance increases in AC as compared to DC which causes larger power loss.

Remember:

- ☑ Skin effect increases with increase in frequency, conductor diameter and permeability.

Proximity Effect

When two or more conductors are in proximity, their electromagnetic field interact with each other, with the result that the current in each of them is redistributed such that the greater current density is concentrated in that part of the strand most remote from the interfering conductor. In each case, a reduced current rating results from the apparent increase of resistance.

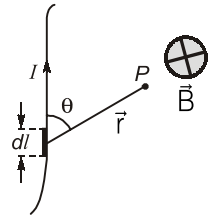
Remember:

- ☑ Proximity effect is more pronounced in case of cable, large conductors and high frequencies.

Magnetic Flux Density**Biot-savart's law**

- Magnetic flux at any point produced by a current carrying element

$$d\vec{B} = \frac{\mu}{4\pi} \frac{I d\vec{l} \times (\vec{r})}{r^3}$$



where, $dB \rightarrow$ Infinitesimal flux density at point P

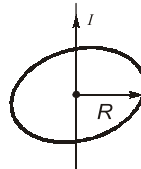
$I \rightarrow$ Current in element ; $dl \rightarrow$ Length of element

$\theta \rightarrow$ Angle between current direction and radius vector to P

$r \rightarrow$ Radius vector ; $\mu \rightarrow$ Permeability of medium

- Magnetic flux density B at any point to an infinite conductor.

$$B = \frac{\mu I}{2\pi R}$$



where, $R =$ Radial distance of the point from the conductor.

Note:

The direction of the flux density is normal to the plane containing the conductor and radius vector R .

Ampere's law , $\oint H \cdot dl = I_{\text{enclosed}}$

where, $H \rightarrow$ Magnetic field intensity
 $I \rightarrow$ R.M.S. value of current enclosed by an amperian loop.

Relation Between Magnetic Flux Density and Magnetic Field Intensity

$$B = \mu H, \mu = \mu_0 \mu_r$$

where, $\mu_0 \rightarrow 4\pi \times 10^{-7} \text{ H/m}$ = Permeability of free space
 $\mu_r \rightarrow$ Relative permeability of the medium
 $= 1$ (for non magnetic material)

Inductance

Inductance of an inductor is the ratio of its total magnetic flux linkages to the current I through the inductor.

$$L = \frac{N\Psi_m}{I} = \frac{\lambda}{I} \text{ Henry}$$

where, $\Psi_m \rightarrow$ Magnetic flux linkages through a single turn
 $N \rightarrow$ Total number of turns ; $\lambda \rightarrow$ Total magnetic flux linkages

Above formulae is valid for a medium in which the permeability is constant.

Remember:

The permeability of ferrous medium is not constant. For such cases the inductance is defined as the ratio of infinitesimal change in flux linkage to the infinitesimal change in current producing it

$$L = \frac{d\lambda}{dI} \text{ Henry}$$

- Flux linkages within the conductor : $\Psi_{\text{int}} = \frac{\mu I}{8\pi} \text{ Wb-T/m}$

where, $\Psi_{\text{int}} \rightarrow$ Total internal flux linkages ; $I \rightarrow$ R.M.S. value of current.

$$\Psi_{\text{int}} = 0.5I \times 10^{-7} \text{ Wb-T/m}$$

- Inductance of the conductor, contributed by flux within the conductor:

$$L_{\text{int}} = 0.5 \times 10^{-7} \text{ H/m} \quad \text{as} \quad L_{\text{int}} = \frac{\Psi_{\text{int}}}{I}$$

- Flux linkages outside the conductor

$$\Psi_{12} = \frac{\mu I}{2\pi} \ln\left(\frac{D_2}{D_1}\right) \text{ Wb-T/m}$$

$$\text{for } \mu_r = 1 : \Psi_{12} = 2 \times 10^{-7} \ln\left(\frac{D_2}{D_1}\right) \text{ Wb-T/m}$$

where $\Psi_{12} \rightarrow$ Total flux linkages between points 1 and 2

- Inductance of the conductor, contributed by flux between points 1 and 2:

$$L_{12} = 2 \times 10^{-7} \ln \left(\frac{D_2}{D_1} \right) \text{ H/m}$$

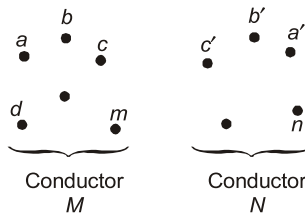
- Inductance of a single phase two wire line:
$$L = 4 \times 10^{-7} \ln \left(\frac{D}{r'} \right) \text{ H/m}$$

where, $D \rightarrow$ Distance between two solid conductors of same radii r

$r' \rightarrow$ Radius of fictitious conductor = $0.7788r$

Inductance of Composite Conductor Lines

Conductor M consists of m similar parallel sub-conductors and conductor N consists of n similar parallel sub-conductors.



(Single phase line having composite conductors)

If line current is I , then each strand of conductor M carries a current I/m and each strand of conductor N carries a current of $-I/n$ (the conductor N being the return conductor).

$$L_M = 2 \times 10^{-7} \times \ln \frac{[(D_{aa'} D_{ab'} \dots D_{an}) (D_{ba'} D_{bb'} \dots D_{bn}) \dots (D_{ma'} D_{mb'} \dots D_{mn})]^{1/mn}}{[(D_{aa} D_{ab} \dots D_{am}) (D_{ba} D_{bb} \dots D_{bm}) \dots (D_{ma} D_{mb} \dots D_{mm})]^{1/m^2}} \text{ H/m}$$

where, $L_M \rightarrow$ inductance of conductor M

$$L = 2 \times 10^{-7} \ln \left(\frac{\text{GMD}}{\text{GMR}} \right)$$

Remember:

- GMD = mn^{th} root of the product of mn distances (known as the geometric mean distance between conductor M and conductor N and denoted by D_m).
- GMR = $(m^2)^{\text{th}}$ root of the product of m^2 distances these being the distances from each sub-conductor of conductor M to every other sub-conductor of conductor M (including $D_{aa}, D_{bb}, \dots, D_{mm}$).
- GMR = Geometric mean radius (denoted by D_s), which depends on radius of conductors and does not effected by unequal spacing of conductors.
- $D_{aa} = 0.7788$ times the radius of sub-conductor ' a '.

Inductance of 3- ϕ Line With Equivalent Spacing.

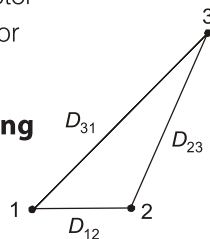
Assuming balanced currents, i.e., $(I_a + I_b + I_c = 0)$

$$L_a = 2 \times 10^{-7} \ln \left(\frac{D}{r'} \right) \text{ H/m}$$

where, $L_a \rightarrow$ Inductance of phase
 $D \rightarrow$ Distance between any two phases
 $r' \rightarrow 0.7788r =$ Radius of fictitious conductor
 $\rightarrow 0.7788$ times the radius of conductor
 $L_a \rightarrow L_b = L_c$ (Because of symmetry)

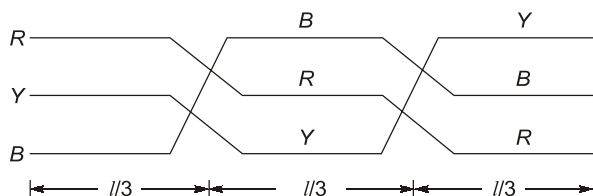
Inductance of 3- ϕ line with unsymmetrical spacing

In this case the lines are transposed.



Transposition of transmission line

- Whenever 3 ϕ unsymmetrical line running parallel and neighbour to the communication line it cause interference in the communication line.
- In order to eliminate the communication interference transposition of line is recommended.
- Change the position of power conductor at regular interval with equidistance for a given line length, so that the position of power conductor is replaced by its successive phase conductor.



Advantages of Transposition

- Net resultant flux ϕ_r which link with communication line become zero.
- GMD/phase equal.
- L/phase equal.
- I/phase equal.
- Flux per phase equal.

Note:

- ☑ Transposition of transmission line is an old technique. The radio interference is eliminated by completely insulating any one of the phases.

Inductance of Phase-1

$$L_1 = 2 \times 10^{-7} \ln \left(\frac{D_{eq}}{r'} \right) \text{ H/m}$$

where, $L_1 \rightarrow$ inductance of phase 1

$$D_{eq} \rightarrow \sqrt[3]{D_{12}D_{23}D_{31}} = \text{Equivalent spacing} \\ = \text{Geometric mean of the distance of the line.}$$

Inductance of Bundled Conductor Lines

- For a two conductor (duplex) arrangement

$$D_s^b = \sqrt[4]{(D_s \cdot d)^2} = \sqrt{D_s \cdot d}$$

- For a three conductor (triplex) arrangement

$$D_s^b = \sqrt[9]{(D_s \cdot d \cdot d)^3} = \sqrt[3]{D_s \cdot d^2}$$

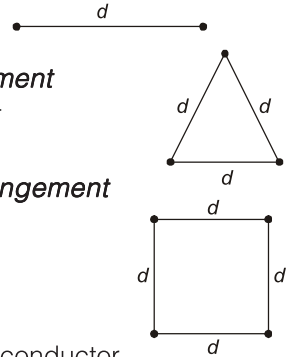
- For a four-conductor (quadruplex) arrangement

$$D_s^b = \sqrt[16]{(D_s \cdot d \cdot d \cdot d \sqrt{2})^4} \\ = 1.09 \times \sqrt[4]{D_s \cdot d^3}$$

where, D_s^b = Geometric mean radius of bundled conductor

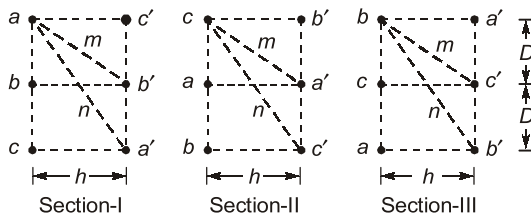
D_s = Geometric mean radius of each sub-conductor of bundle

d = Spacing between the sub-conductors of a bundle



Remember:

- ☑ Inductance of bundled conductor line is less than the inductance of the line with one conductor per phase.
 - ☑ GMD depends only on the distance between the conductors and is independent of radius of conductors.
-

Inductance of Double Circuit 3- ϕ Line**Inductance per phase per metre length**

$$L = 2 \times 10^{-7} \ln \left[2^{1/6} \left(\frac{D}{r'} \right)^{1/6} \cdot \left(\frac{m}{n} \right)^{1/3} \right] \text{ H/phase/m}$$

Mutual Inductance

Mutual inductance is defined as the flux linkages of one circuit due to the current in the second circuit per-ampere of current in the second circuit. If the current I_2 produces λ_{12} flux linkages with circuit 1. The mutual inductance is

$$M_{12} = \frac{\lambda_{12}}{I_2} \text{ Henry}$$

Electrical Field and Potential Difference

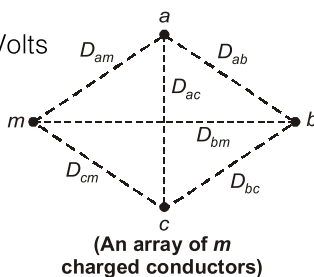
- The lines of electric flux originate on the positive charges on one conductor and terminate on the negative charges on the other conductor.
- If a long straight cylindrical conductor has a uniform charge throughout its length and is isolated from other charges.
- Electric field intensity E at any point, $E = \frac{q}{2\pi\epsilon \cdot x}$ V/m
 where, $q \rightarrow$ Charge on conductor per unit length
 $\epsilon \rightarrow$ Permittivity of the medium
 $x \rightarrow$ Distance from conductor to the point under consideration.
- The potential difference between two points

$$V_{xy} = \frac{q}{2\pi\epsilon} \ln\left(\frac{D_y}{D_x}\right) \text{ Volts}$$

where, $D_x, D_y \rightarrow$ Distance of point x and y from charge q
 $q \rightarrow$ Charge per unit length

- The potential difference between two conductor of an array of parallel conductors

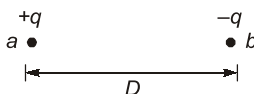
$$V_{ab} = \frac{1}{2\pi\epsilon} \left[q_a \ln \frac{D_{ab}}{r_a} + q_b \ln \frac{r_b}{D_{ba}} + q_c \ln \frac{D_{cb}}{D_{ca}} + \dots + q_m \ln \frac{D_{mb}}{D_{ma}} \right]$$



Capacitance

Capacitance of Two Wire Line

$$C_{ab} = \frac{\pi\epsilon}{\ln\left(\frac{D}{r}\right)} \text{ F/m}$$



where, $C_{ab} \rightarrow$ Line to line capacitance

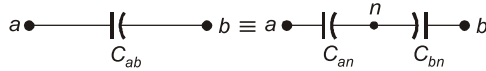
$q \rightarrow$ Charge per unit length; $r \rightarrow$ Radius of conductor a and b

If the conductor have different radii, $r = \sqrt{r_a \cdot r_b}$

where, $r_a, r_b \rightarrow$ Radius of conductor ' a ' and conductor ' b ' respectively.

Line to neutral capacitance

$$C_{an} = C_{bn} = 2C_{ab}$$

**Charging Current**

- The current caused by the alternate charging and discharging of the line due to alternating voltage is called **charging current** of the line.

Note:

- ☑ Charging current flows in a line even when the line is open circuited and affects the voltage drop, efficiency and power factor of the line.

Charging Current for 1- ϕ line

$$I_C = j\omega C_{an} V_{an} \text{ A/m / Phase}$$

where, $V_{an} \rightarrow$ Potential difference between conductor a and neutral

$\omega \rightarrow$ Frequency of alternating voltage

Capacitance of 3- ϕ line with equilateral spacing

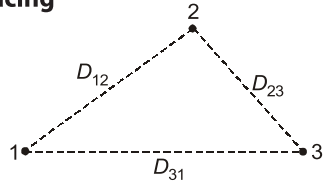
$$C_n = \frac{0.02412}{\log\left(\frac{D}{r}\right)} \mu\text{F/km} \quad \text{or} \quad C_n = \frac{2\pi \epsilon}{\ln\left(\frac{D}{r}\right)}$$

where, $C_n \rightarrow$ Line to neutral capacitance ; $D \rightarrow$ Spacing between conductors ; $r \rightarrow$ Radius of each conductor

Charging current per phase, $I_C = j\omega C_n V_{an}$

Capacitance of 3- ϕ line with asymmetrical spacing

$$C_n = \frac{2\pi \epsilon}{\ln\left(\frac{D_{eq}}{r}\right)} \mu\text{F/km}$$



where,

$$D_{eq} = \sqrt[3]{D_{12} D_{23} D_{31}}$$

Capacitance of bundled conductor lines

$$C_n = \frac{2\pi \epsilon}{\ln\left(\frac{D_{eq}}{D_{sc}^b}\right)} \mu\text{F/km}$$

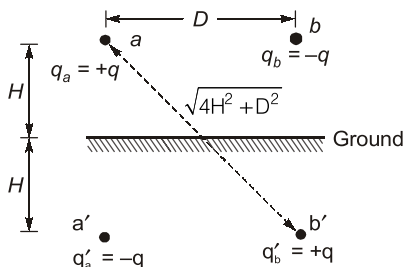
Self GMD of Bundle Conductors

- For a two conductor bundle, $D_{sc}^b = \sqrt{rd}$
- For a three conductor bundle, $D_{sc}^b = \sqrt[3]{(r \times d \times d)^3} = \sqrt[3]{rd^2}$
- For a four conductor bundle, $D_{sc}^b = \sqrt[4]{(r \times d \times d \times \sqrt{2}d)^4} = 1.09\sqrt[4]{rd^3}$

Effect of Ground on Line Capacitance (Method of Images)

The presence of ground alters the electric field of a line and hence affect the line capacitance.

For 1- ϕ line:

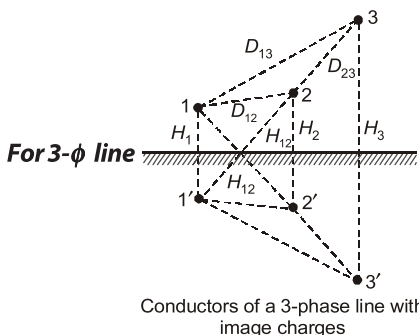


$$C_{ab} = \frac{\pi \epsilon}{\ln \left[\frac{D}{r \left(1 + \frac{D^2}{4H^2} \right)^{0.5}} \right]} \text{ F/m}$$

where, $H \rightarrow$ Height of conductor from ground

$$C_{an} = 2C_{ab} = \frac{2\pi \epsilon}{\ln \left(\frac{D}{r'} \right)} \text{ F/m ;}$$

$$r' = r \sqrt{1 + \left(\frac{D}{2H} \right)^2}$$



$$C_n = \frac{2\pi \epsilon}{\ln \left(\frac{D_{eq}}{r} \right) - \ln \left[\frac{\sqrt[3]{H_{12}H_{23}H_{31}}}{\sqrt[3]{H_1H_2H_3}} \right]}$$

where, H_1, H_2, H_3 , and H_{12}, H_{23}, H_{31} are shown in figure.
 C_n is in $\mu\text{F/km}$.

Note:

☒ Presence of ground increases the line capacitance by small amount.